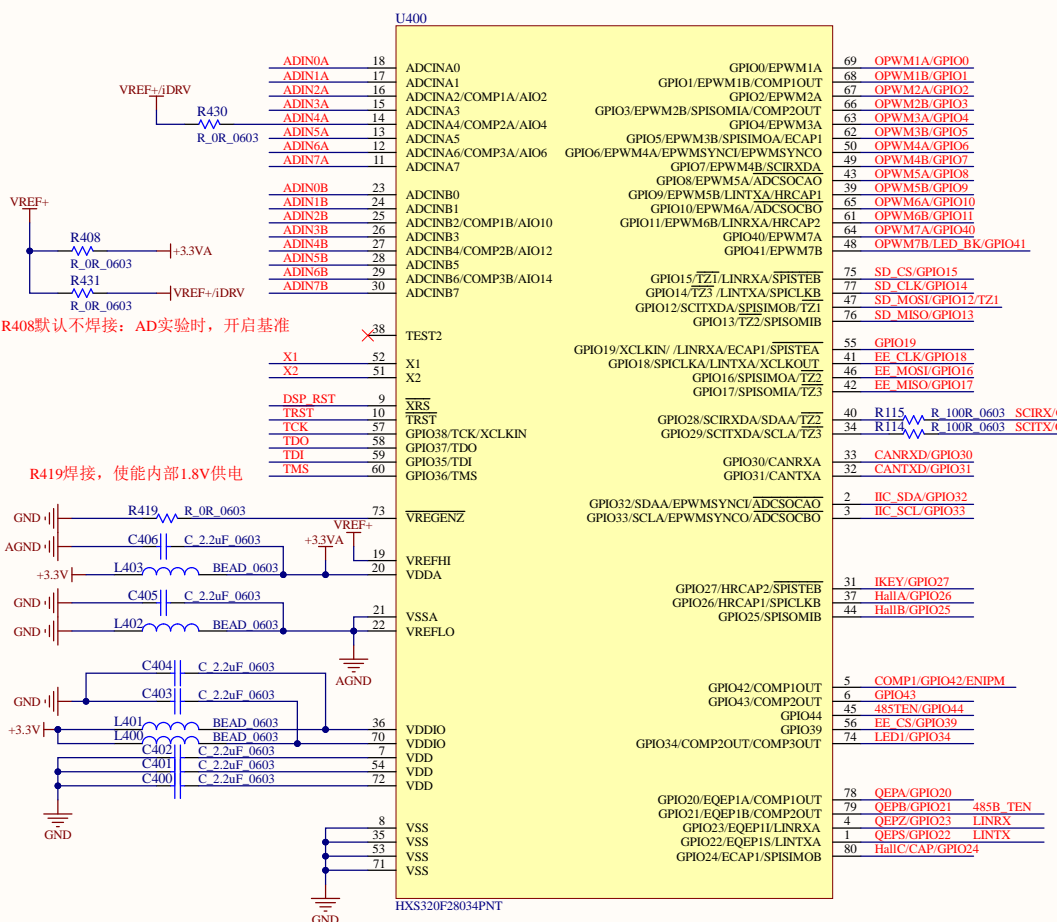


U11不焊接,AD使用内部基准源

参考: 通用的复位电路

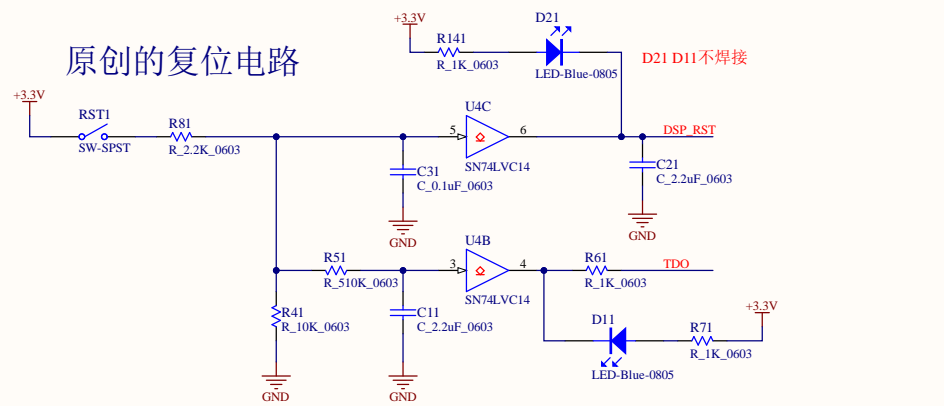


R408默认不焊接: AD实验时, 开启基准

R419焊接, 使能内部1.8V供电

HXS320F28034PNT

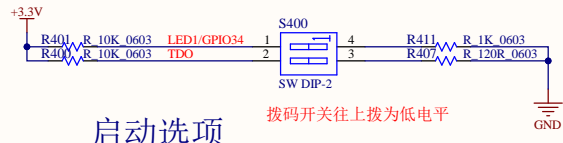
### 原创的复位电路



智能串口下载法, 无需操作拨码开关

步骤: 长按3秒RST->HX Downloader 下载->下载完毕->短按RST->DSP运行

- 串口下载通过通过HX-LINK-Downloader软件实现
- 短按(点一下), DSP复位
- 长按4秒钟, DSP进入串口下载模式, 等待串口下载, DSP停止运行FLASH程序

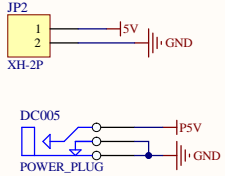


### 启动选项

Boot Mode Selection  
 MODE GPIO37/TDO GPIO34 TRST MODE  
 3 1 1 0 GetMode Flash  
 2 1 0 0 Wait  
 1 0 1 0 SCI  
 0 0 0 0 Parallel IO  
 EMU x 1 Emulation Boot

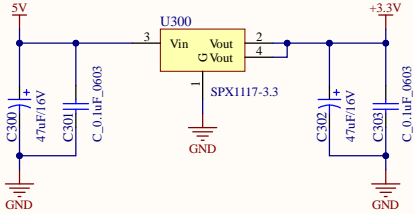
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Date:	6-07-2022	Sheet of
File:	D:\Haawking\...\HXS320F28034PNT.Sch	Drawn By:

JP2可以接电机驱动板的JP2实现驱动板给控制板供电

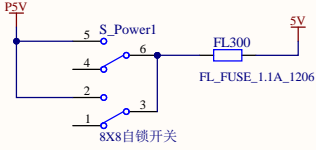


黑色电源座：内正(5V)外负

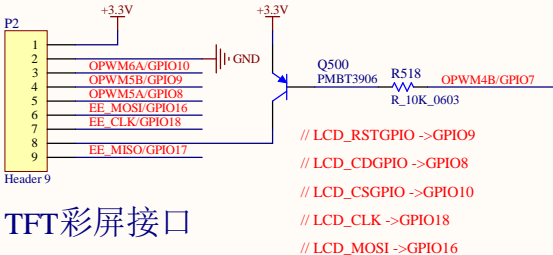
### 电源



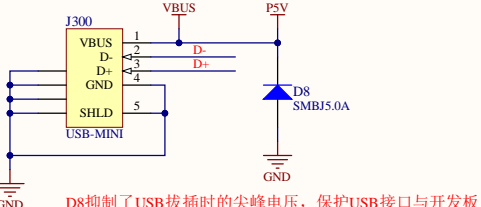
3.3V电源指示灯



按下开关，开发板供电

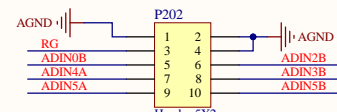


### TFT彩屏接口



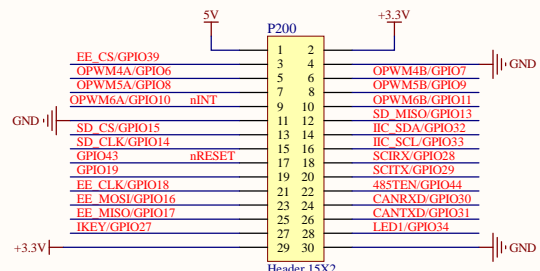
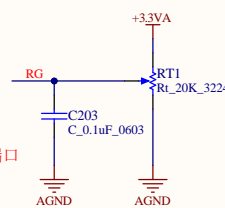
D8抑制了USB拔插时的尖峰电压，保护USB接口与开发板

### 外扩模拟口



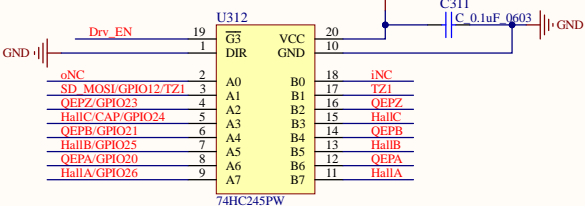
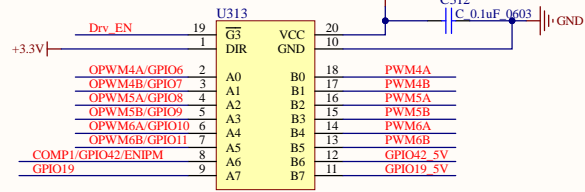
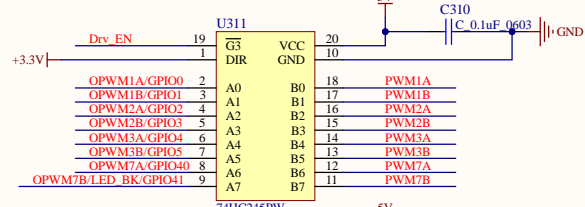
跳线帽短接3-5脚，将可调电阻输出的模拟电压接到AIN0B端口

### 可调电阻

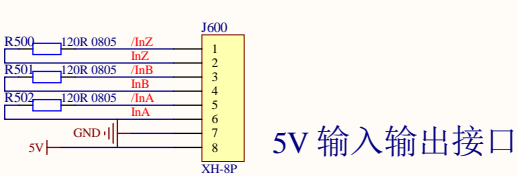
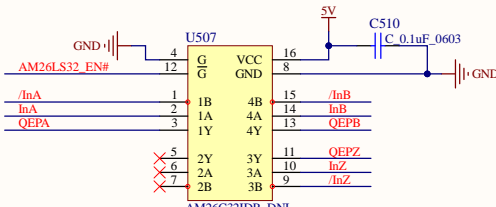


### 外扩IO口

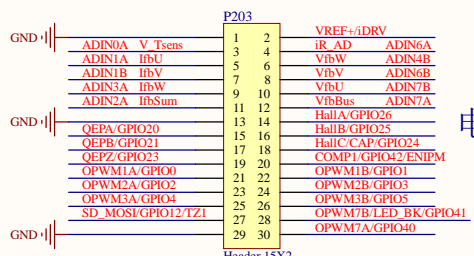
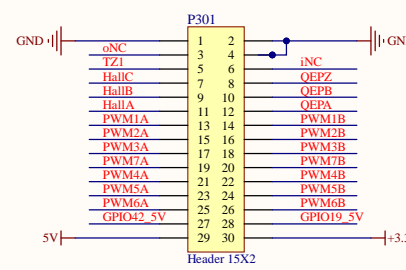
### 3.3V转5V输出 / 5V转3.3V输入



### 编码器差分输入(U507预留不焊接)



### 5V 输入输出接口

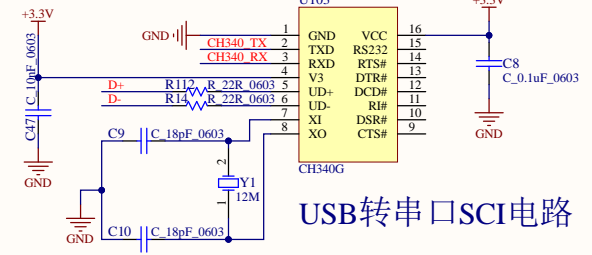
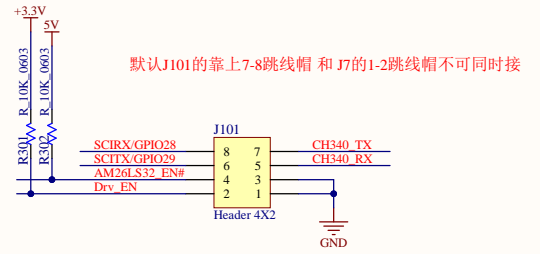
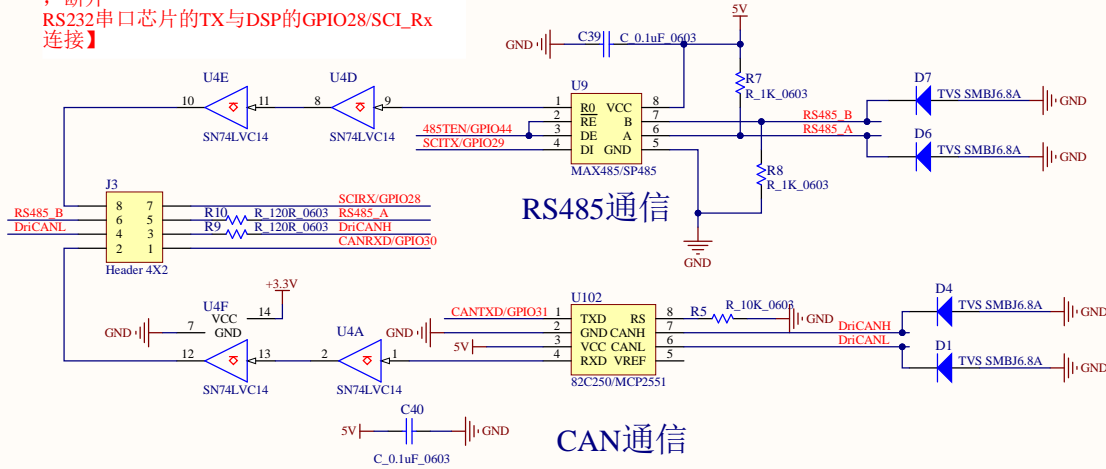


### 外扩IO口兼容电机驱动板接口

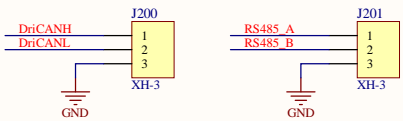
P203兼容电机驱动板30P接口

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Date:	6-07-2022	Sheet of
File:	D:\Haawking\...\POWER_IO.SchDoc	Drawn By:

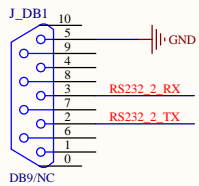
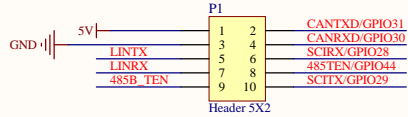
J3的7-8短接，提供RS485的Rx与DSP的GPIO28/SCL\_Rx连接  
**【做RS485通信试验时，取下J7靠上的跳线帽，断开RS232串口芯片的TX与DSP的GPIO28/SCL\_Rx连接】**



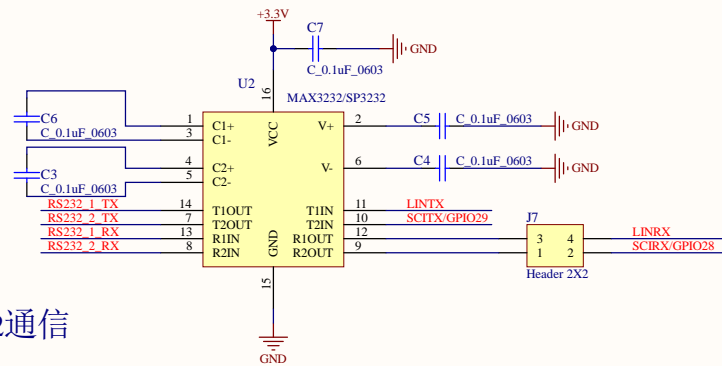
**CAN通信差分接口 RS485通信差分接口**



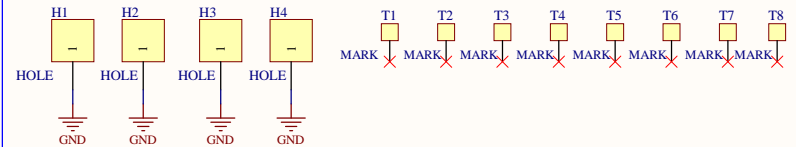
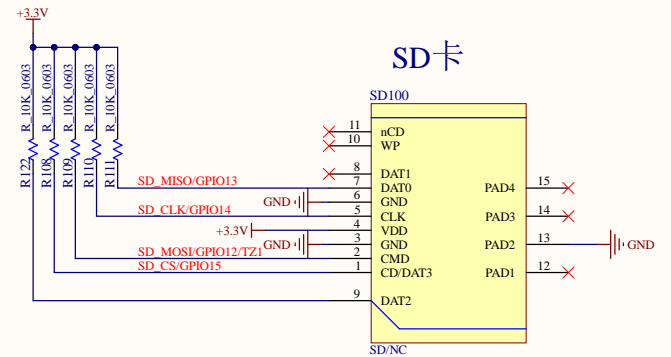
**RS485/CAN隔离接口 P1兼容SI4463无线模块接口**



**RS232通信**

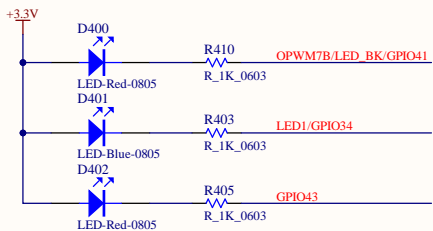


LIN作为通过RS232芯片连到H-4接口，作为第二路RS232串口（LIN复用当做串口功能）  
 默认J101的靠上7-8跳线帽和J7的1-2跳线帽不可同时接  
 采用LIN外设作为RS232通信

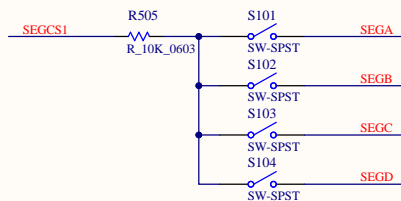
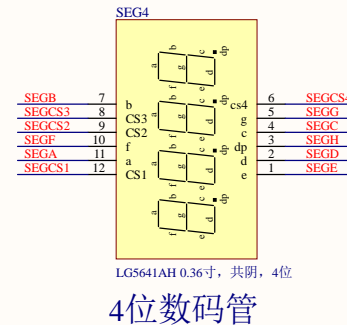
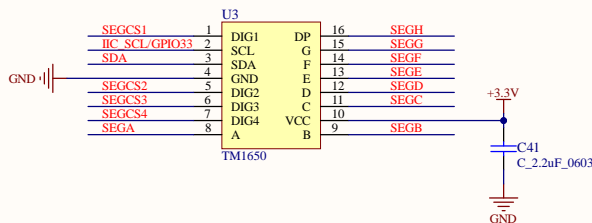


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### 独立的IO LED

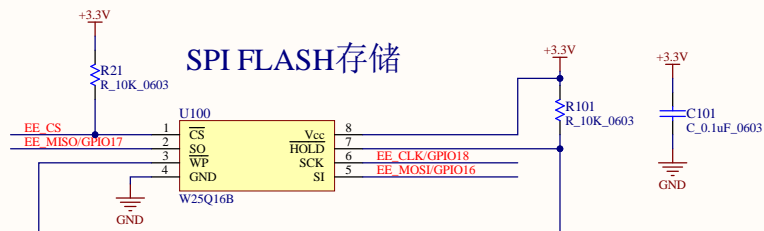


### 数码管驱动芯片



### 4个扫描按键

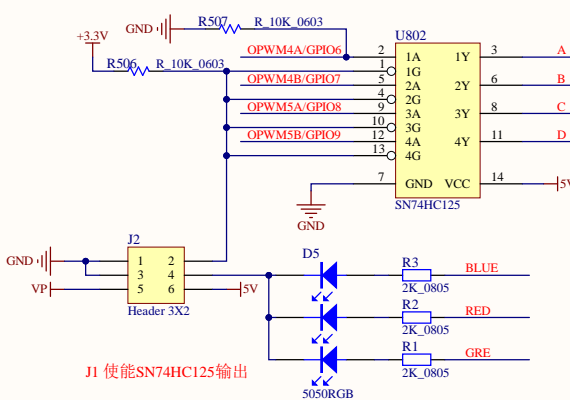
### SPI FLASH存储



### PWM4A/GPIO6 到 PWM5B/GPIO9驱动电路

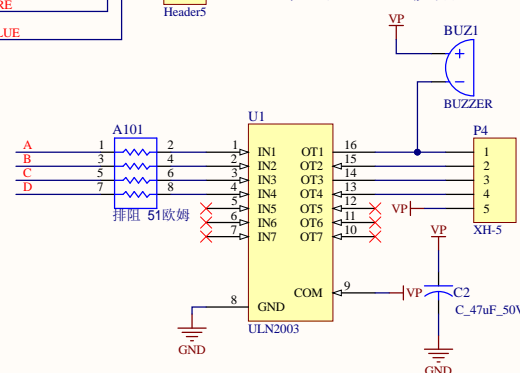
1. 74HC125驱动5050 全彩LED, 高电平LED亮
2. 2003可驱动5线的步进电机或者控制继电器

Tips: 这里建议用户增加4个10k电阻将GPIO6-9下拉到GND, 以保证DSP复位期间, SN74HC125的输出逻辑是低电平。



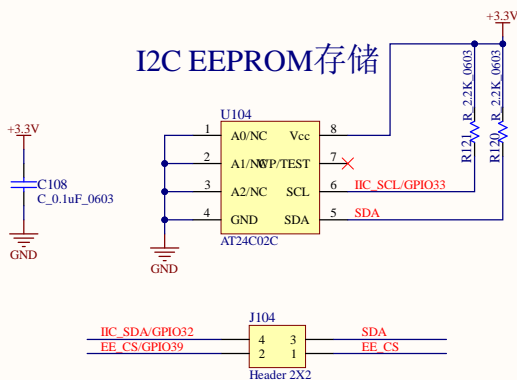
J1 使能SN74HC125输出

J2的5-6用跳线帽短接, 蜂鸣器5V使能

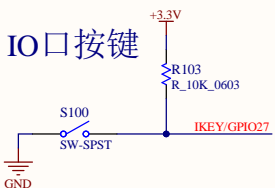


2003集成了7路达林顿管, 这里用了4路  
INx = 1, OTx = 0, 导通到GND  
INx = 0, OTx = 0C, 极电极开路  
这里4路输出可以作为简单的步进电机驱动

### I2C EEPROM存储



### 独立的 IO口按键



### J2左右短接

- 1-2, 使能125输出
- 3-4, 全彩LED使能
- 5-6, 蜂鸣器5V电源使能

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A3		
Date:	6-07-2022	Sheet of
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